

5 Phase Stepping Motor Driver

MC-5514P/5514P-3



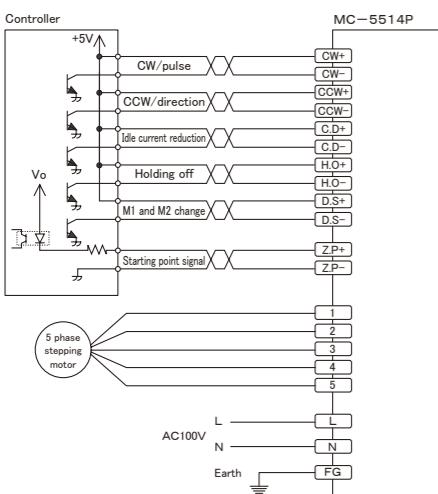
FEATURE

- It is 5 Phase-stepping motor driver of the AC100~115V input.
- Maximum resolution is 1/250 (125,000 pulse per rotation).
- Low vibration drive(Full or Half step). (Except MC-0514P-3)
- Applies to a wide motor to 0.5A/phase-1.4A/phase.
- I/O uses the connector.

SPECIFICATION

Name	5 phase stepping motor driver
Model	MC-5514P , MC-5514P-3
Driving method	Micro step
Input power	AC100~115V ±10% 50/60Hz 3.5A Max.
Drive current	0.5A~1.4A/phase
Division	MC-5514P 1, 2, 4, 5, 8, 10, 16, 20, 25, 40, 50, 80, 100, 125, 200, 250 MC-5514P-3 1, 2, 3, 6, 12, 18, 24, 32, 36, 48, 60, 72, 120, 160, 180, 240
Maximum frequency	500 kpps
Input signal	Optical-isolator input [1]:4~8V , [0]:-8~0.5V Input resistance CW, CCW:300Ω C.D, H.O, D.S:390Ω
Output signal (Z.P.)	Optical-isolator open corrector output Condition ; DC30V or less, 50mA or less
Function	Pulse input mode selector , Micro step angle select , Automatic current reduction , Driving voltage select Initial system check
Insulation resistance	The value is 50MΩ or more,that measured by DC500V Megger Between the AC input and the case.
Withstand voltage	It is not above even if AC1500V is impressed between the AC input and the case for one minute.
Operating temperature range	0~40°C
Operating humidity range	0~85%
Weight	750g

SAMPLE WIRING DIAGRAM



MOTOR

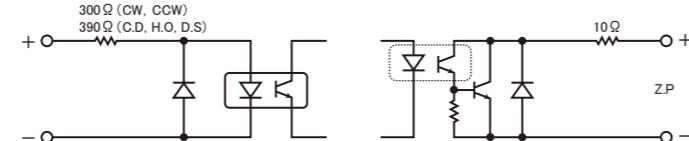
- 5/10 lead 5-Phase stepping motors such as Tamagawa-seiki or Oriental-motor.

See table below for the pin no. of the connector and color of motor leads.

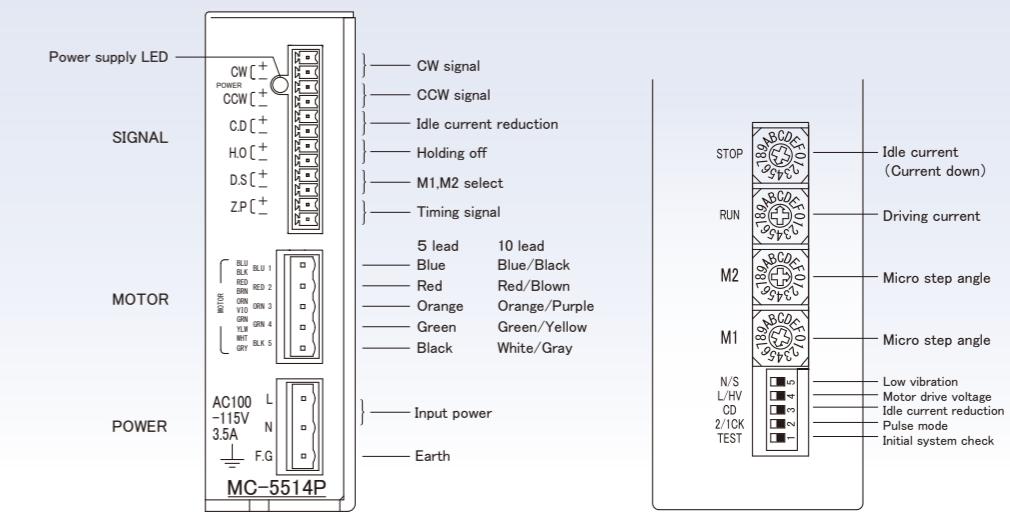
Connector No.	5 lead	10 lead
1	Blue	Blue/Black
2	Red	Red/Blown
3	Orange	Orange/Purple
4	Green	Green/Yellow
5	Black	White/Gray

Note : Please use the wire rod of AWG20(0.5mm²) or more for connecting the motor.

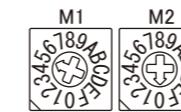
INPUT/OUTPUT CIRCUIT



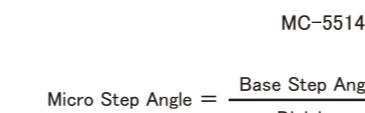
NAME AND FUNCTION



SETTING MICROSTEP RESOLUTION



MC-5514P	SW No.	0	1	2	3	4	5	6	7	8	9
	Division	1	2	4	5	8	10	20	40	80	16
								A	B	C	D
								25	50	100	125



MC-5514P-3	SW No.	0	1	2	3	4	5	6	7	8	9
	Division	1*	2*	3	6	12	18	24	32	36	48
								A	B	C	D
								60	72	120	160

$$\text{Micro Step Angle} = \frac{\text{Base Step Angle}}{\text{Division}}$$

72 divided steps → 0.01 degree

*Does not drive at the low vibration in this case.

SETTING DRIVE CURRENT

The desired drive current is obtained by setting RUN SW as follows.



Drive Current
(RUN : Rotary Switch)

SW No.	0	1	2	3	4	5	6	7	8	9
Current(A)	0.5	0.58	0.66	0.75	0.81	0.88	0.96	1.03	1.1	1.15
	A	B	C	D	E	F				

Example : Drive current = 1.4A/phase.
RUN SW = C

SETTING IDLE CURRENT (CURRENT DOWN)

Idle current is established by setting STOP SW as follows.



Idle Current
(STOP : Rotary Switch)

SW No.	0	1	2	3	4	5	6	7	8	9
Current(%)	27	31	36	40	45	50	54	58	62	66
	A	B	C	D	E	F				

Example : When the drive current is set at 1.4A/Phase, idle current will be 0.7A/Phase at the switch position no. 5 (50%).

DIP SW FUNCTIONS



No.	Indication	Mode	ON	OFF
1	TEST	Initial system check	Rotating (60pps).	Always set to off
2	2/ICK	Pulse mode	One pulse	Two pulse
3	C.D	Idle current reduction	Not active	Activated
4	L/HV	Motor drive voltage	*High speed and high torque	Standard
5	N/S	Low vibration	Low vibration drive	Standard drive

*Please note heat of the motor when driving by high speed and a high torque.