



## **SPECIFICATIONS**

Item No.: ACA826T

Description: High Accuracy Digital Type Dual-Axis Inclinometer

with Full Temperature Compensation

#### **Production implementation standard reference**

- Enterprise quality system standards: ISO9001: 2008 standard (certification number: 128101)
- Tilt sensor production standards: GB / T 191 SJ 20873-2003 inclinometer general specification of Level
- •The Academy of metrology and quality inspection Calibrated in accordance to: JJF1119-2004 Electronic Level calibration Specification
- Software development reference standard: GJB 2786A-2009 military software development General requirements
- Product environmental testing standards: GJB150
- Electromagnetic anti-interference test standards: GB / T 17626
- Version:Ver.09
- Date:2014.4.16





#### **General Description**

ACA826T is a full temperature compensation & high accuracy dual-axis inclinometer which professionally developed by Rion Company to the field of high precision level measurement and leveling field , the maximum measuring range is  $\pm$  3 °, high resolution 0.0005 °, can completely replace the traditional high-precision level meter. Digital signal transmission, matched with professional computer software, data measure and record correctly ,output interface RS485, RS232, TTL, PWM or CAN 2.0B optional.Non-contact installation features make ACA826T with superior system integration, convenient installation only need fix the sensor on the measured surface by screws , then can automatically calculate the object horizontal inclined angle, easy to use .With strong ability resistance to external electromagnetic interference and to withstand shock and vibration,in the domestic counterparts products with absolute competitive advantage.

#### **Features**

- •Dual-Axis Inclinometer
- •Size:L92×W48×H36mm
- •Wide temperature working: -40~+85°C
- •Resolution: 0.0005°
- •Highly anti-vibration performance >2000g
- •Output mode RS232、RS485、RS422、TTL、CAN 2.0 are optional
- Measuring Range :±1~±3° optional
- Wide voltage input: 9∼36V
- •IP67 protection class
- Water-proof air-plug

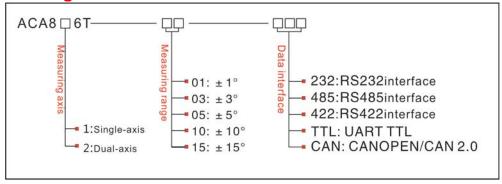
#### **Application:**

- •Engineering vehicles automatic leveling
- •Laser equipment position
- •Underground drill posture navigation
- Precise machine tool level control

- •Bridge & dam detection
- •Medical facilities angle control
- Railway gauging rule , gauge equipment leveling
- •Geological equipment inclined monitoring
- •Directional satellite communications antenna pitching angle measurement



#### **Ordering information:**



E.g: ACA826T-01-232: Dual-axis/Standard/±01°Measuring range/RS232 output

#### **Technical Data**

Parameters	Conditions	ACA826T-03	ACA826T-10	ACA826T-15	unit
unit Measuring range		±03	±10	±15	•
Measuring axis		XY	XY	XY	
Resolution		0.0005	0.0005	0.0005	0
Absolute accuracy		0.001	0.005	0.006	0
Long term stability		0.002	0.003	0.005	
Zero	-40~85°	±0.0008	±0.0008	±0.0008	%℃
temperature					
coefficient					
Sensitivity	-40∼85°	≤50	≤50	≤50	ppm/℃
temperature					
coefficient					
Power on time		0.5	0.5	0.5	S
Response time		0.05	0.05	0.05	S
Output rate	5Hz、15Hz、35Hz、50Hz can be setting				
Ouput signal	RS232/RS485/RS422/TTL/CAN				
Electromagnetic	According to EN61000 and GBT17626				
compatibility					
MTBF	≥50000hours/times				
Insulation	≥100M				
Resistance					
Shockproof	100g@11ms、Times/Axis(half sinusoid)				
Anti-vibration	10grms、10~1000Hz				
Protection glass	IP67				
Cables	Standard 1M length、wearproof、wide temperature、				
	Shielded cables4*0.4mm2 air-plug connector				
Weight	150g(without cable )				

#### **Electronic Characteristics**

Parameters	Conditions	Min	Standard	Max	Unit
Power supply	Standard	9	12、24	36	V
	customized		Other voltage		V
Working current	No-load		50		mA
Working temperature		-40		+85	$^{\circ}$
Store temperature		-55		+100	$\mathbb{C}$

#### **Key words:**

Resolution: Refers to the sensor in measuring range to detect and identify the smallest changed value.

Absolute accuracy: Refers to in the normal temperature circumstances, the sensor absolute linearity,

repeatability, hysteresis, zero deviation, and transverse error comprehensive error.

Long term stability: Refers to the sensors in normal temperature conditions, the deviation between the maximum and minimum values after a year's long time work.

Response time: Refers to the sensor in an angle change, the sensor output value reached the

standard time required.

#### **Mechanical Parameters**

o Connectors: 1m cable with air-plug connector (customized)

Protection glass: IP67(air plug connector) Enclosure material: Aluminum Oxide

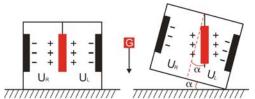
o Installation: 4\*M4 screws

2\*3mm plug position(optional)



#### **Working Principle**

Adopt the European import of core control unit, using the capacitive micro pendulum principle and the earth gravity principle, when the inclination unit is tilted, the Earth's gravity on the corresponding pendulum will produce a component of gravity, corresponding to the electric capacity will change, by enlarge the amount of electric capacity, filtering and after conversion then get the inclination.

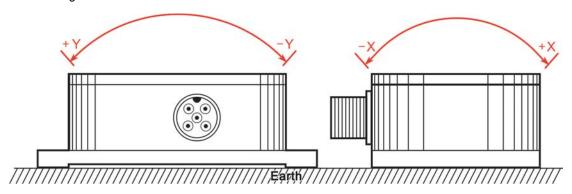


 $U_{\text{R}}$ ,  $U_{\text{L}}$ Respectively is the pendulum left plate and the right plate corresponding to their respective voltage between theelectrodes, when the tilt sensor is tilted,  $U_{\text{R}}$ ,  $U_{\text{L}}$  Will change according to certain rules, so  $f(U_{\text{R}},U_{\text{L}})$ , on the inclination of  $\alpha$  function:

 $\alpha = (U_R, U_L, )$ 

#### **Measuring Directions&Fix**

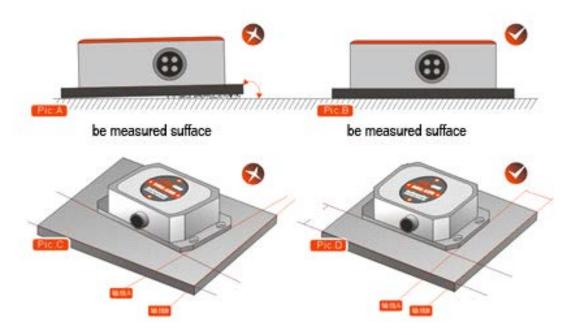
The installation must guarantee the product bottom is parallel to measured face, and reduce the influence of dynamic and acceleration to the sensor. This product can be installed horizontally or mounted vertically (mounted vertically selection is only applicable to the single axis), for installation please refer to the following scheme.



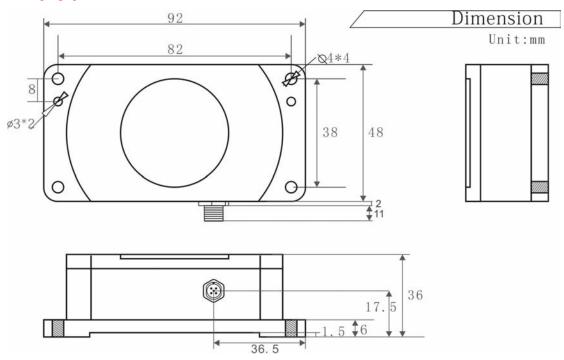
#### **Production installation notes:**

Please follow the correct way to install tilt sensor, incorrect installation can cause measurement errors, with particular attention to the "surface", "line":: 1) The Sensor mounting surface and the measured surface must be fixed closely, smoothly, stability,if mounting surface uneven likely to cause the sensor to measure the angle error. See Figure Pic.AB

2) The sensor axis and the measured axis must be parallel ,the two axes do not produce the angle as much as possible. See Figure Pic.CD

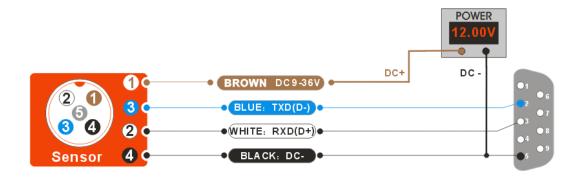


#### **Dimension**



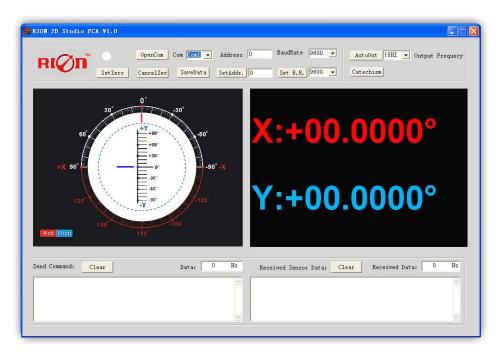
Size: L92×W48×H36mm **Electrical Connection** 

Line	BLACK	WHITE	BLUE	BROWN	GRAY
color functio	GND	RS232(RXD)	RS232(TXD)	Vcc 9∼36V	FACTORY
Turictio	Power Negative	Or RS485(D+)	Or RS485(D-)	Power supply positive	Use only



#### **RION serial port tester software**

You can download the RION angle debugging software from RION's official website for the preliminary angle debugging, also you Can download public version of the serial port assistant software on line for using .



Open/Close: Open and close COM port;

Com: Select the the device corresponding to the COM port

Address: Fill in the sensor current address code, the factory default is 00

Set Address: Set the sensor address code input box on the right to enter the desired address code, click Set Addr button

Save Data: Save the data, click here data can be synchronized Save angle data, the file is stored by default in the C: ---- COMDATA file

Set Zero: Set relative zero, the sensor current angle is 00.00 degrees

Cancel Zero: Unset the relative zero, to restore the sensor to the factory absolute zero;

Baud Rate: Select the sense baud rate , the factory default is 9600;

Set Baud Rate: Set the sensor baud rate, on the right of the selection box to select corresponding baud rate then click SetB.R. button;

Auto Output: Switch the sensor to automatically output mode, in the automatic output mode can be filled with different output frequency in Hz;

Catechism: The sensor switch to answer pattern, such as choosing the answer type, must input "send command" (command, please refer to the specification) on the left of "Send Command" input box, but also can fill in the transmit frequency in the Send Data, the unit Hz;

Note: after install the RION's debugging software, if can not open, please operate by the following steps (please appear to the administrator status to operate):

- Copy these three files mscomm.srg、mscomm32.ocx、mscomm32.dep from the folder to C:/Windows/system32 path below。
- 2) Click "Start" "run" -- regsvr32 mscomm32.ocx, You are prompted to install successful dialog.





#### **Product Protocol**

#### 1.DATA FRAME FORMAT:

(8 bits date, 1 bit stop, No check, Default baud rate 9600)

Identifier	Date Length	Address code	Command word	Date domain	Check sum
(1byte)	(1byte)	(1byte)	(1byte)		(1byte)
68					

Date format: hexadecimal Identifier: Fixed68

Data length: From data length to check sum (including check sum) length

Address code: Accumulating module address, Default:00

Date domain will be changed according to the content and length of command word

Check sum: Data length. Address code. Command word and data domain sum, No carry.

#### 二、COMMAND word analysis

Desc.	Meaning/Example	Description
0X04	Meanwhile read angle command E.g: 68 04 00 04 08	Data domain(0byte) No Data domain command
0X84	sensor data response	data field(9byte)
	Eg:	68 is prefix of data packets, fixed.
	68 10 00 84 <b>00 00 20 08 10 00 25</b>	10 is data lenght, fixed.
	28 10 35 00 80 DE	00 is address code, revisable.
		84 is command code, fixed.
		00 00 20 08 the four red bytes are the X axis
		returned angle value in compact BCD code. the high
		order <b>0</b> of first byte is sign bit(0: positive; 1:
		negative), 00 0 are three digit integer value, 20 08
		are four decimal digit. other axis data analysis
		method is similar.
		the angle is +000.2008 deg by analizing.
		10 00 25 28, the four blue bytes are Y axis returned
		angle value, analysis method is similar to X axis
		10 35 00 80, the four green bytes are internal
		temperature value, analysis method is similar to X
		axis.
		DE check sum, hexadecimal sum of all data,
		exclude prefix 68,
		if surpass one byte, pick low-order.
0X05	Setting relative/absolute ZERO:	Data domain
	Can set the current angle to	(1byte)
	Zero degree, relative	00: absolute ZERO
	measurement, can also be set to	01: relative ZERO
	absolute ex-factory zero, power off	
	save	
	E.g: <b>68 05 00 05 00 0A</b>	
0X85	Sensor answer reply command	Data domain(1byte)

	E.g: <b>68 05 00 85 00 8A</b>	Data domain in the number means the sensor
		response results
		00 Setting successfully
		FF Setting failure
0X0B	Setting communication rate	Data domain(1byte)
	E.g: <i>68 05 00 0B 03 13</i>	Baud rate: default :9600
	The command setting is effective	00 means 2400
	after power off then restart	01 means 4800
	( power off with save function)	02 means 9600
	,	03 means 19200
		04 means 38400
		05 means 115200
0X8B	Sensor answer reply command	Data domain (1byte)
UNUD	E.G:68 05 00 8B 90	Data domain in the number means the sensor
	L.G.00 00 00 0D 00	response results
		·
охос	Satting concer cutnut made	
UXUC	Setting sensor output mode	Data domain
	Response rule;	(1byte) Factory default: 00
	Need upper computer send	00 Answer reply mode
	reading angle command , the	01 5Hz Automatical output mode
	sensor answer	02 15Hz Automatical output mode
	the corresponding angle	03 25Hz Automatical output mode
	Automatic output rule:	04 35Hz Automatical output mode
	The sensor with power on can	05 50Hz Automatical output mode
	Automatically output X angle , The	
	output frequency base on what be	
	setted, if you need output High	
	frequency, please set baud rate as	
	115200	
	(Power off with save function)	
	E.g: <b>68 05 00 0C 00 11</b>	
0X8C	The sensor answer reply	Data domain (1byte)
	command	Data domain in the number means the sensor
	E.g: 68 05 00 8C 00 91	response results
		00 Success FF Failure
OXOF	Setting module address	Data domain
	command	(1byte) XX Module address
	The sensor default address is 00,	Address from 00 to EF range
	1, such as a plurality of sensor	Note: All products have a common address :FF,
	to be connected with a bus cable,	If forget the address what has been set during
	e.g RS485.requires each sensor is	operation , can use FF address to operate the
	set to a different address, in order	product can still normally respond
	to achieve control and response	product our our normany respond
	angle.	
	2, If successfully changed the new	
	address, follow all of the	
	commands and responding	
	Packet address code has to switch	
1	to the new address code which	





	already changed then to be	
	effective, otherwise the sensor will	
	not respond to commands.(power	
	off with save function)	
	E.g: <b>68 05 00 0F 01 15</b>	
	Setting the address to 01	
	68 05 FF 0F 00 13	
	Use the common address to reset	
	address to 00	
0X8F	The sensor answer reply	Data domain(1byte),
	command	Data domain in the number means the sensor
	E.g: 68 05 00 8F 94	response results
		00 Success FF Failure
OXOD	Query relative/absolute ZERO	Data domain (0byte)
	Used to query the sensor current	No data domain commands
	ZERO mode is relative ZERO	
	or absolute ZERO	
	E.g : <b>68 04 00 0D 11</b>	
0X8D	The sensor answer reply	Data domain (1byte),
	command	Data domain in the number means the sensor
	E.g: <b>68 05 00 8D 00 92</b>	response results
		00 Absolute ZERO
		01 Relative ZERO



XMore products information, please refer to the company's Website :  $\underline{www.rion\text{-tech.net}}$ 





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✓ 倾角传感器 ✓ 倾角(调平)开关 ✓ 数显水平仪 ✓ 陀螺仪✓ 三维电子罗盘 ✓ 加速度计 ✓ 航姿参考系统 ✓ 寻北仪

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